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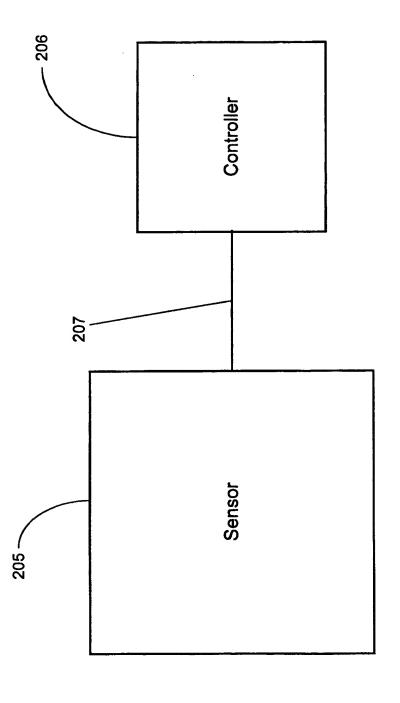
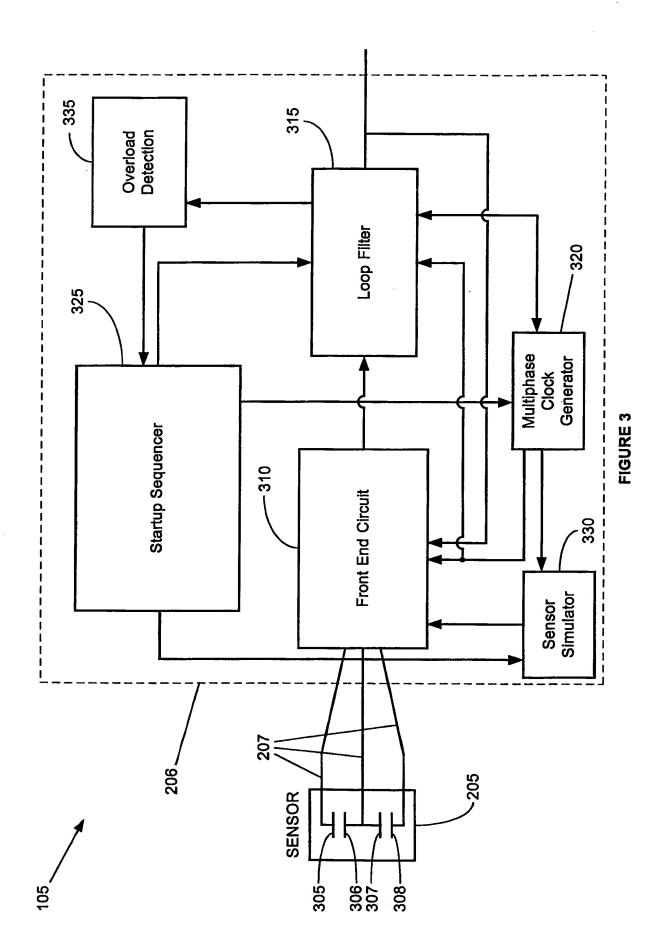
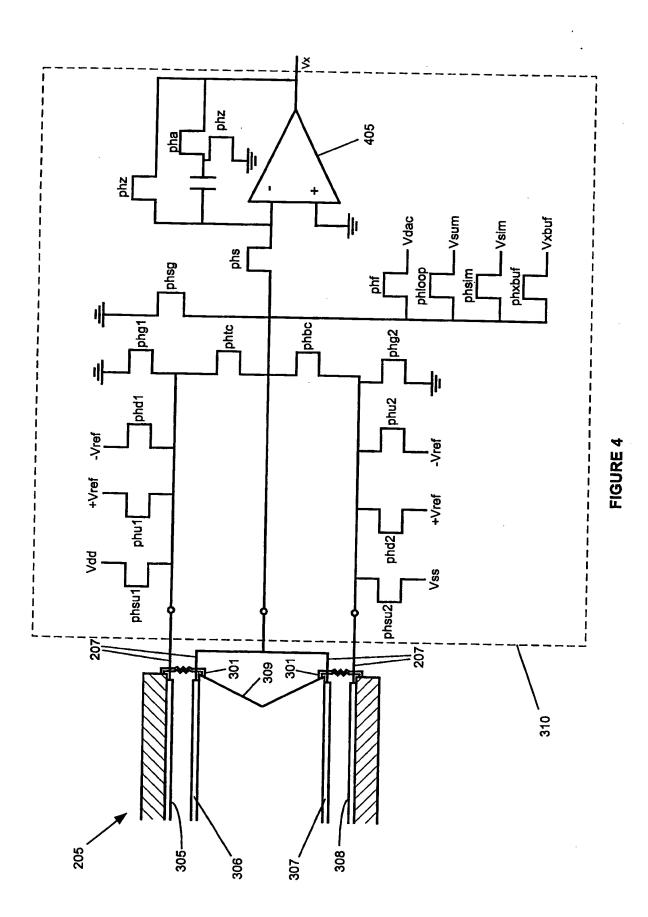
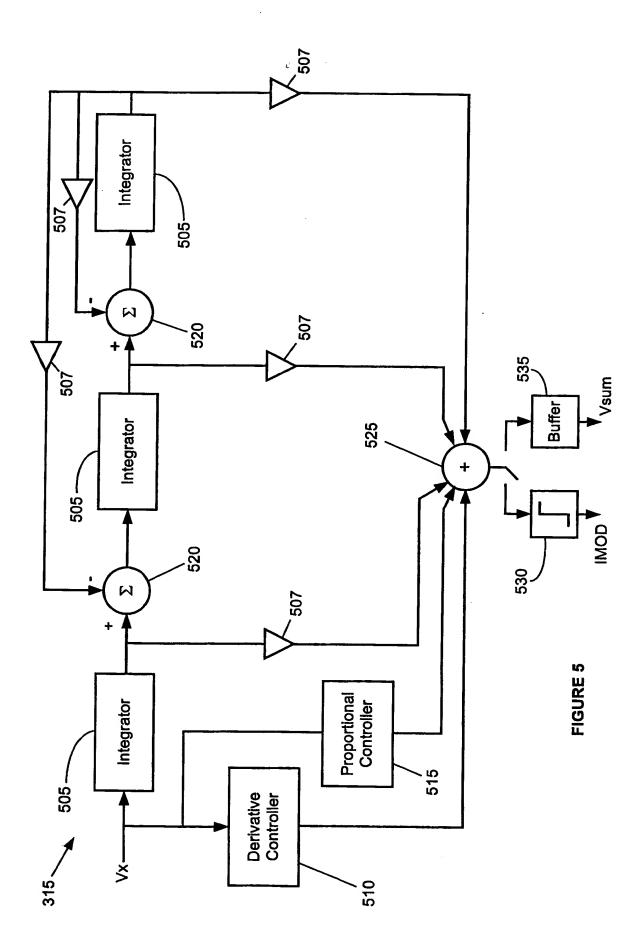


FIGURE 2

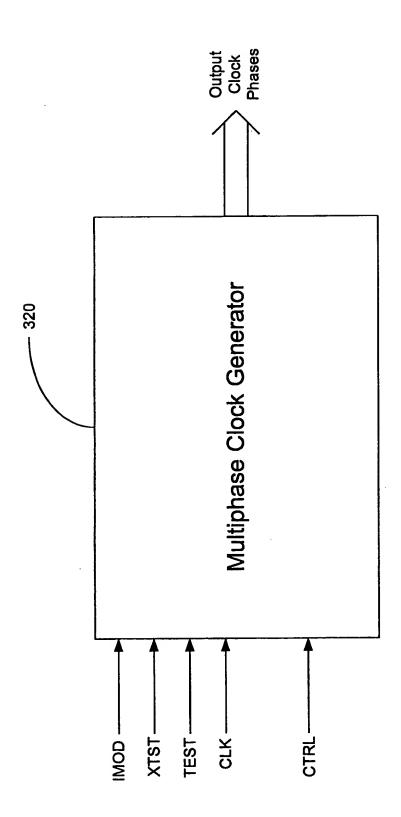




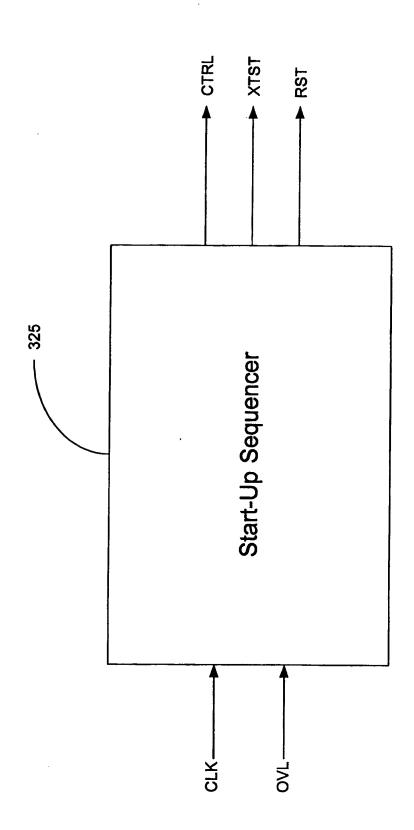




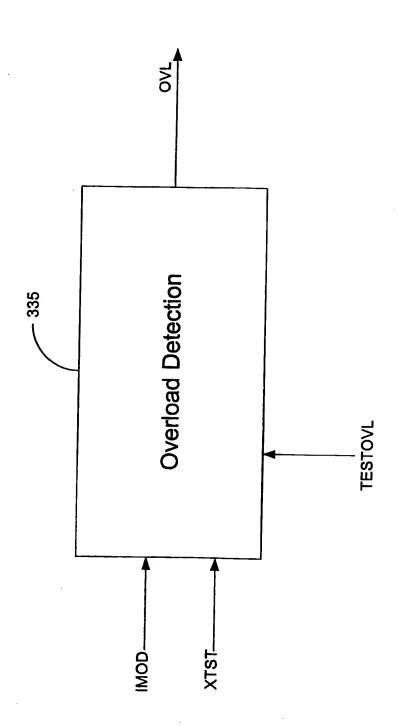




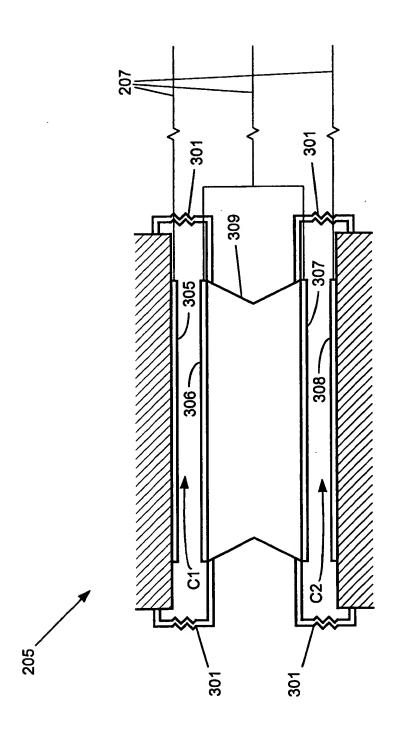




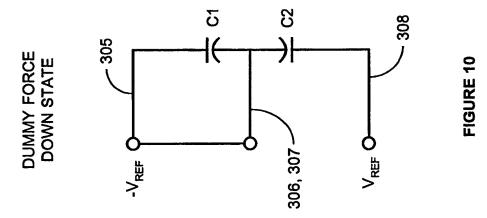


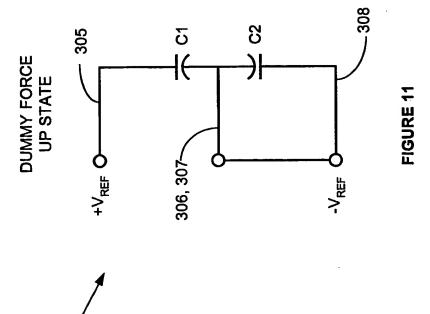




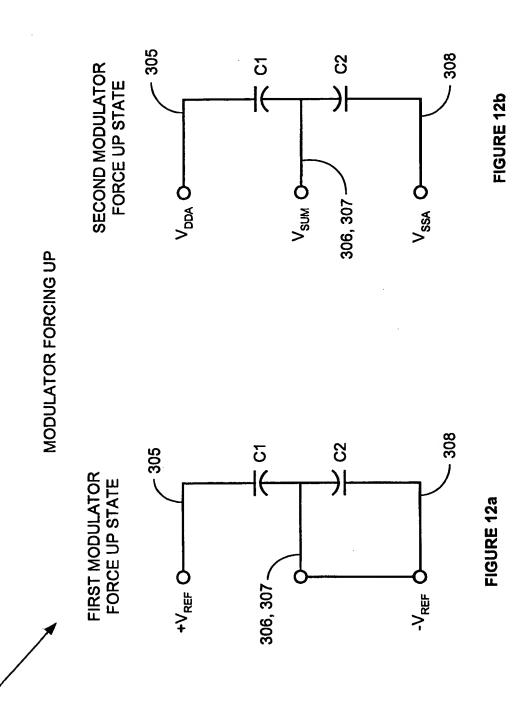


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FIGURE 12d

FIGURE 12c

MODULATOR FORCING DOWN

205

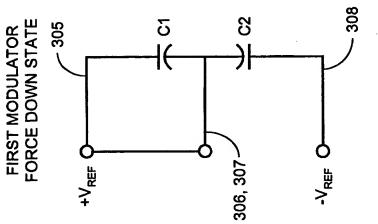
SECOND MODULATOR
FORCE DOWN STATE

VDDA O

VSUM

VSUM

VSSA



205

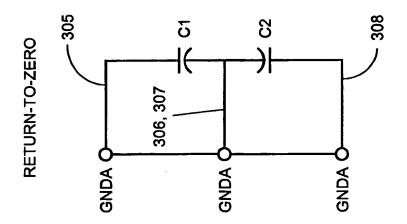


FIGURE 13

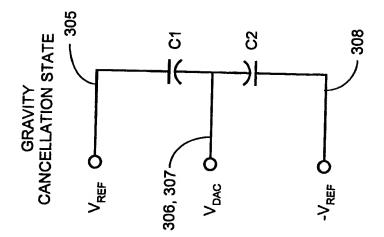
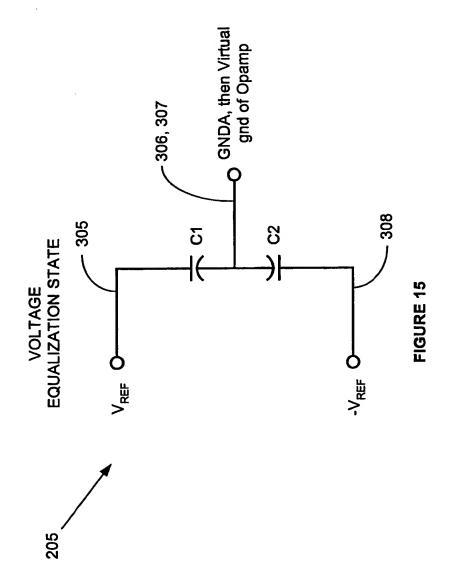


FIGURE 14





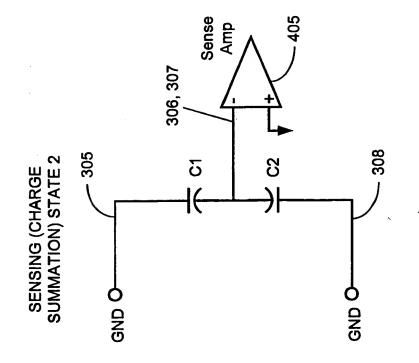
**62** 

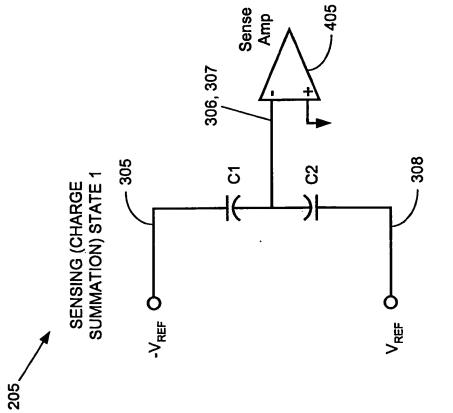
**17** 

FIGURE 16b

FIGURE 16a

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SENSING STATE 2	off	off	off	off	off	off	8	6	JJO	off	Jo	JJO	off	JJO	JJo	Б	off	uo
SENSING STATE 1	off	off	off	off	no	5	off	off	off	off	off	off	off	off	off	uo	off	on
VOLTAGE EQUALIZATION STATE	off	JJ 0	uo	Б	off	off	off	off.	off	off	on, then off	off	off	JJO	JJO	off, then on	ь	JJO
GRAVITY CANCELLATION STATE	off	off	Б	uo	off	JJO	JJO	JJO	off	JJO	JJO	uo	До	Щo	μο	Jo	LIO	ДO
RETURN-TO- ZERO STATE	off	off	off	off	off	off	uo	ПO	no	60	uo	off	off	off	off	Jo	ь	off
SECOND MODULATOR FORCE DOWN STATE	ь	6	off	off	щo	μο	μο	щo	щo	Jo	ДO	JJO	ио	JJO	Дo	JJO .	uo	JJo
FIRST MODULATOR FORCE DOWN	off	off	off	off	uo	uo	ijО	ЭЙ	uo	Off	JJO	JJO	JJO	JJO	μο	μο	ио	JJO
SECOND MODULATOR FORCE UP STATE	6	Б	off	Jo	off	Щo	Щo	ДO	JJO	ЭĤ	off	щo	uo	JJO	μο	JJO	ио	що
FIRST MODULATOR FORCE UP STATE	off	off	ПО	on	off	off	off	off	off	ьо	off	Jo	Пo	off	Jo	μο	ио	JJO
DUMMY FORCE DOWN STATE	off	off	off	off	no	ПО	Щo	JJO	ио	JJO	off	що	JJO	off	JJO	μο	uo	Щo
DUMMY FORCE UP STATE	ЭÚ	Off	ક	ь	off	JIO .	off	JJO	Jjo	E	off	JJO	JJO	yo	JJo	Jo	Б	JJo
	phsu1	phsu2	phu1	phu2	phd1	phd2	phg1	phg2	phtc	phbc	bsyd	phf	doolyd	phsim	phxbuf	syd	zyd	pha



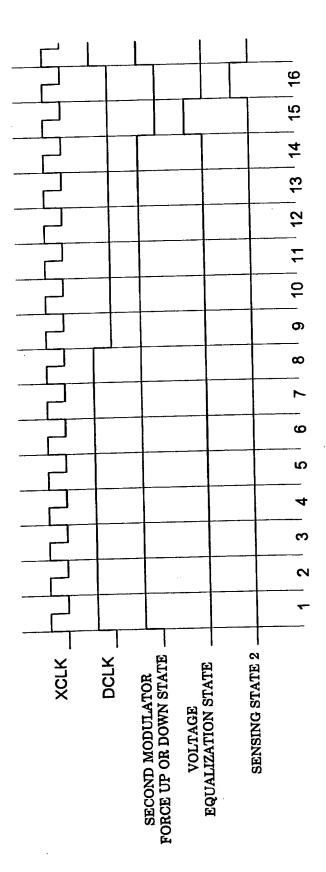
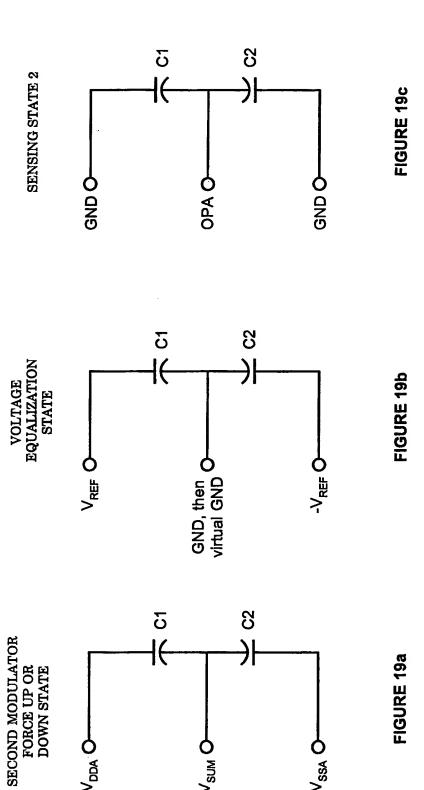


FIGURE 18

Clock Periods



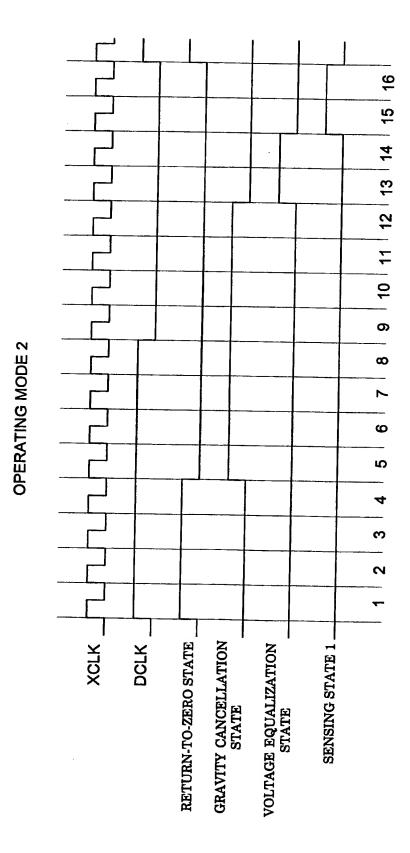
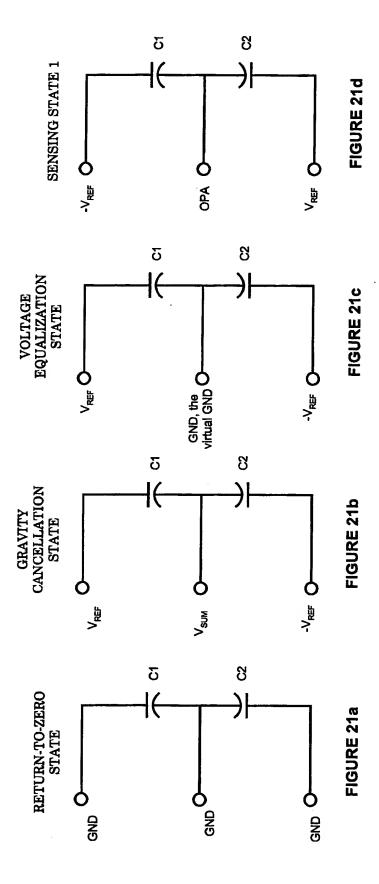
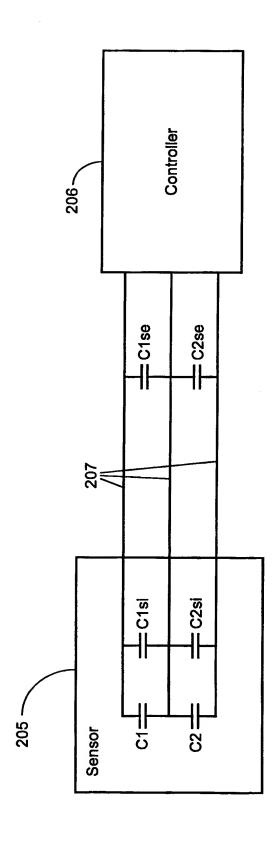


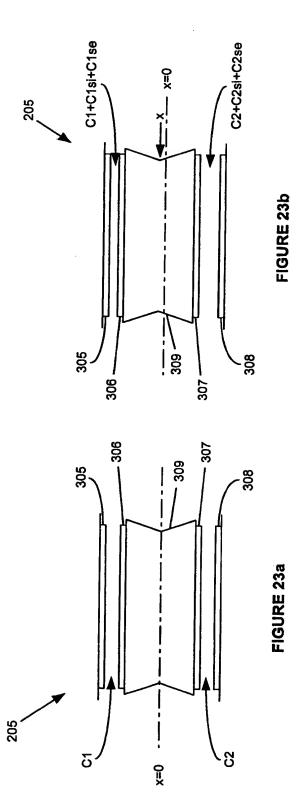
FIGURE 20

Clock Periods









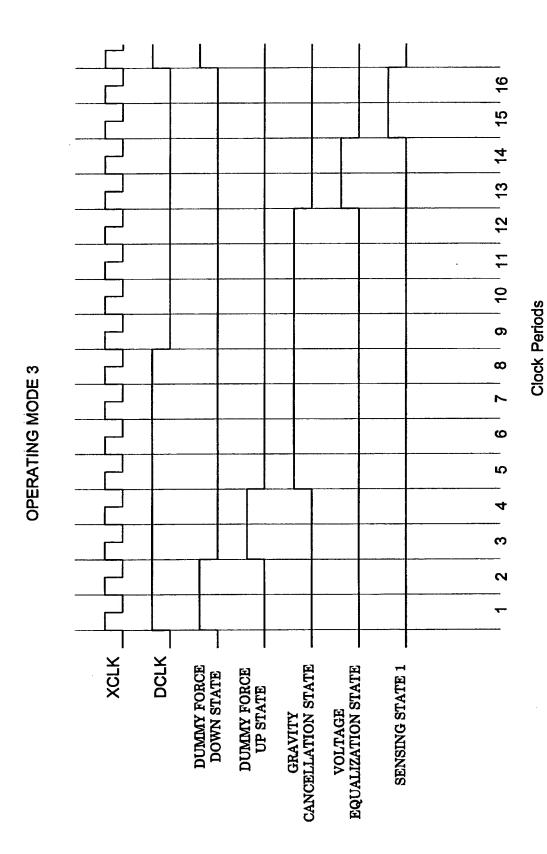
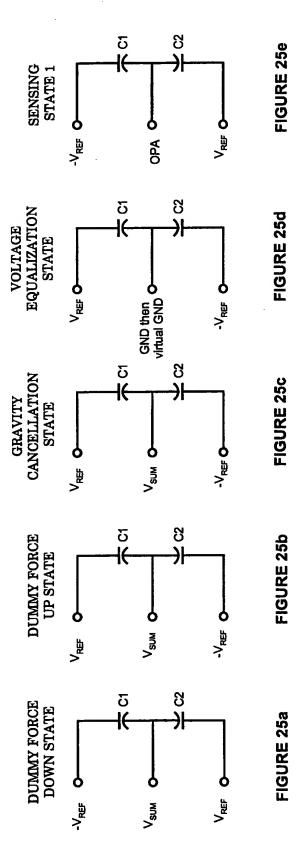


FIGURE 24



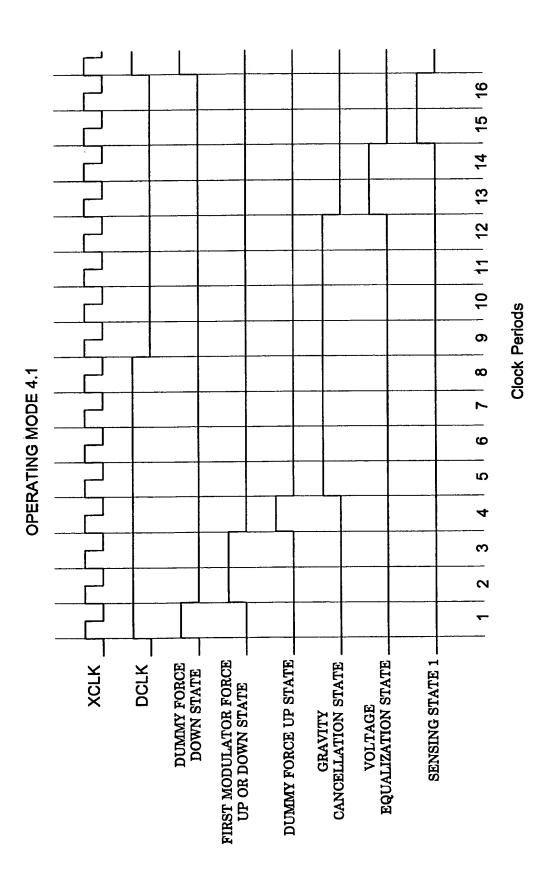
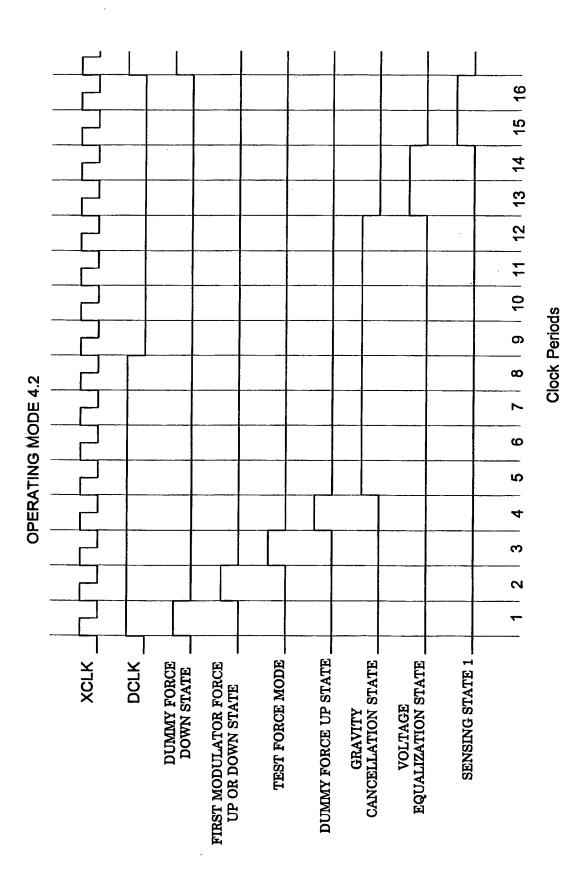


FIGURE 26



**FIGURE 27** 

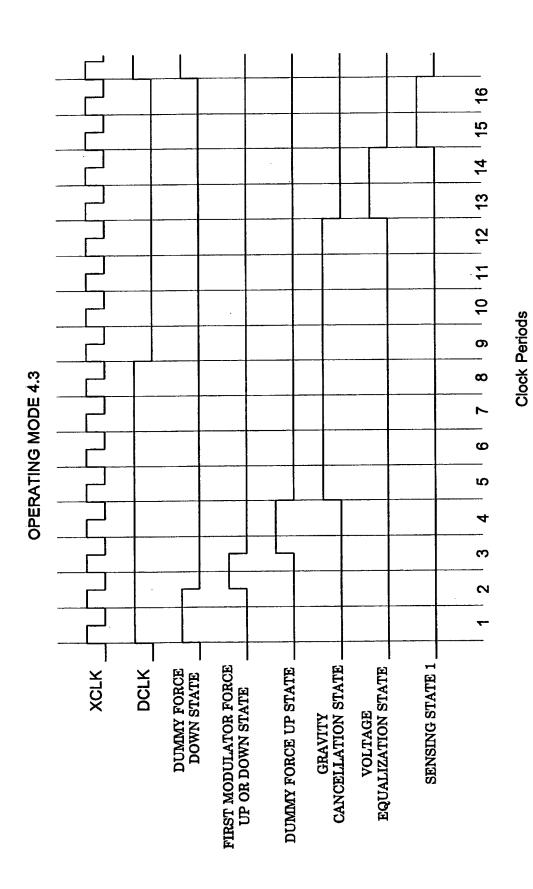
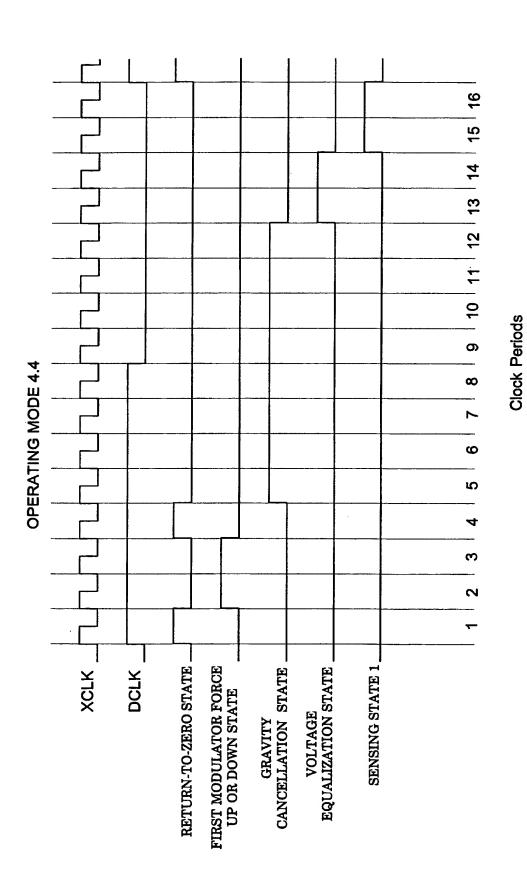


FIGURE 28



**FIGURE 29** 

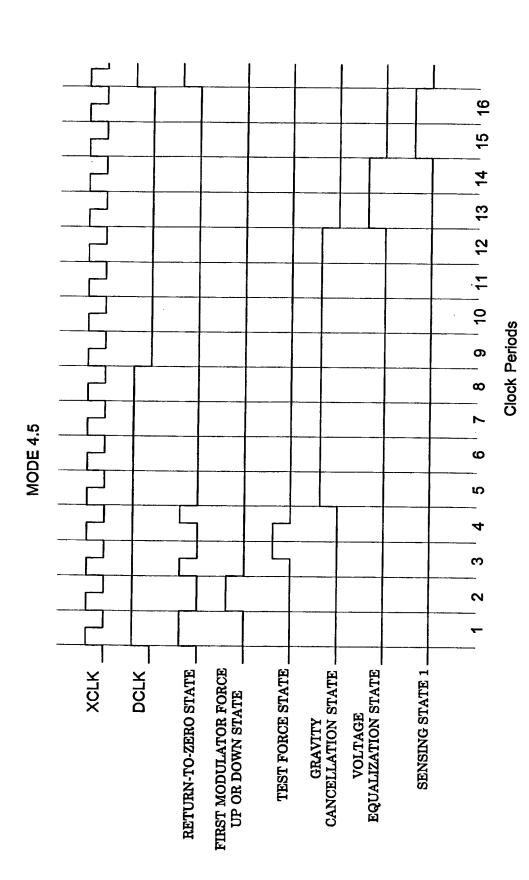


FIGURE 30

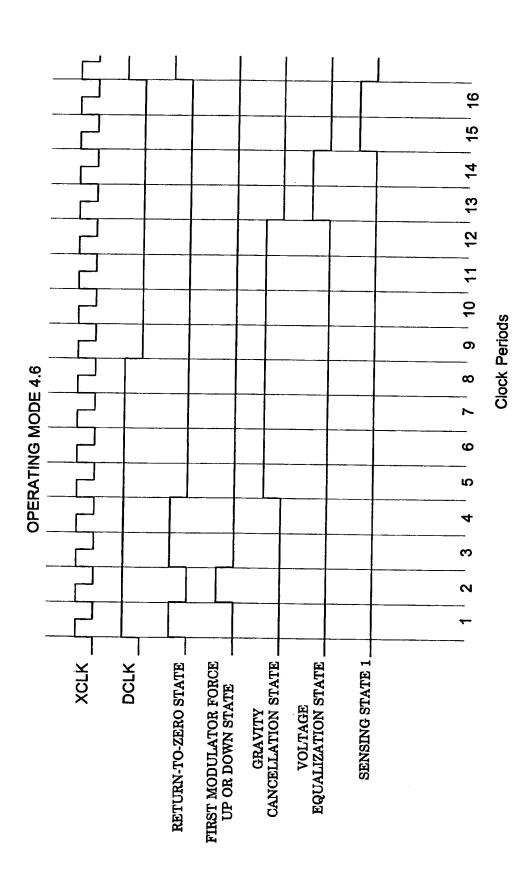


FIGURE 31

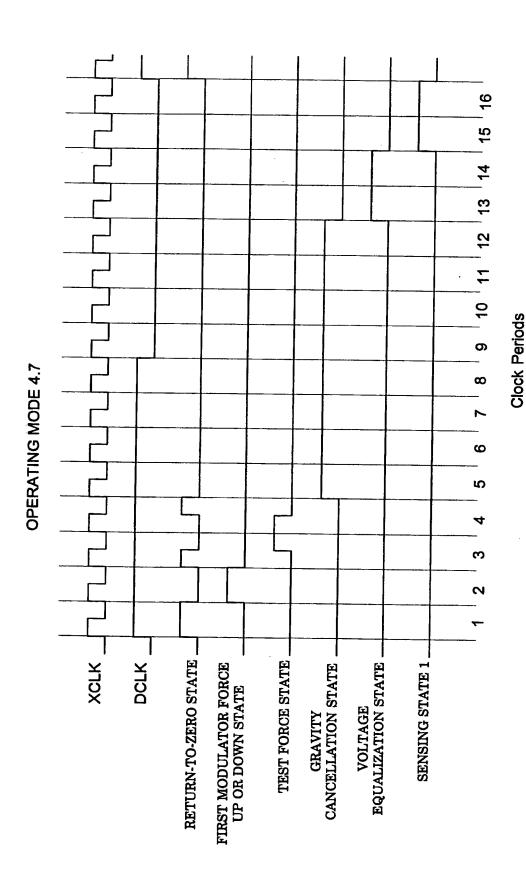


FIGURE 32

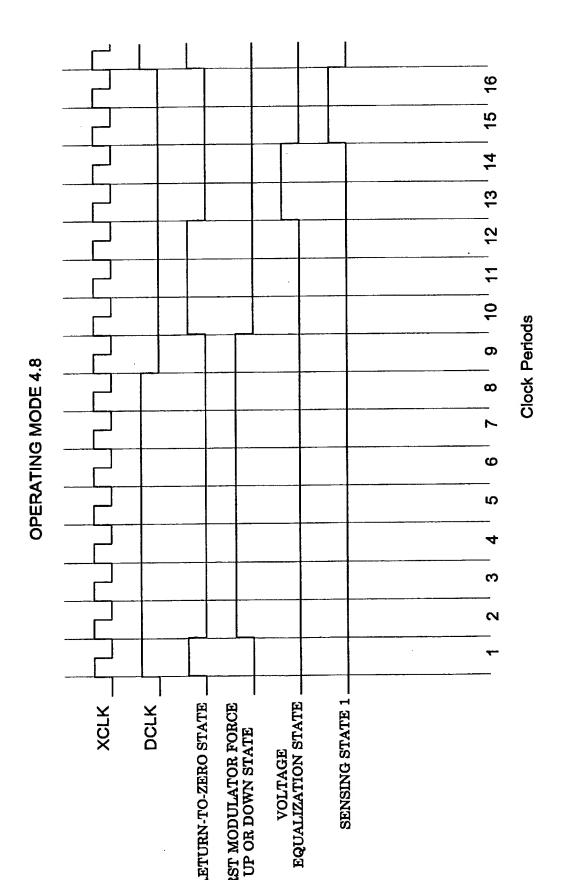


FIGURE 33

Start-Up w/o stray capacitances

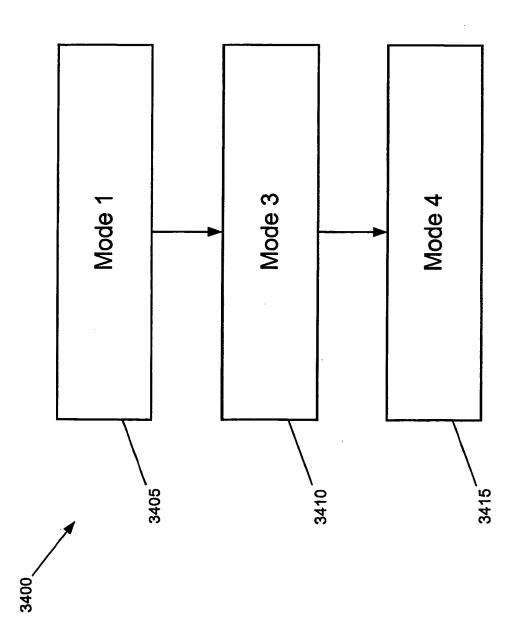
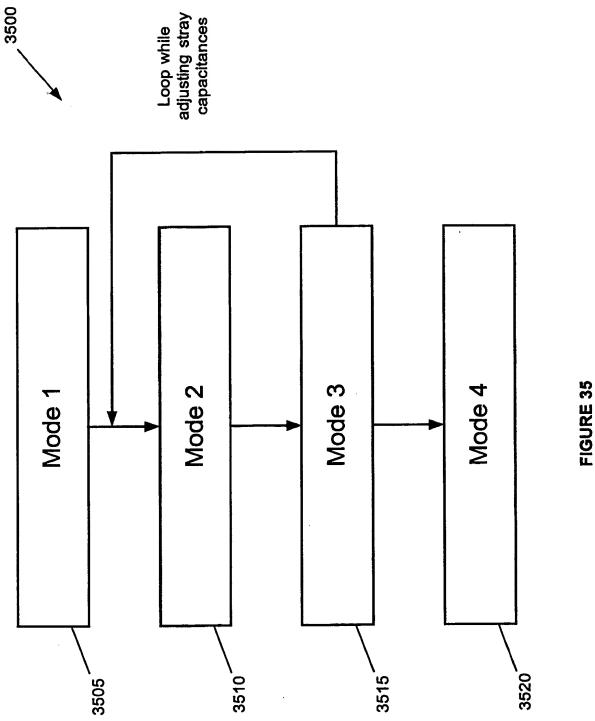


FIGURE 34

tart-Up w/stray capacitances



Start-Up w/o stray capacitance calibration (Analog Output)

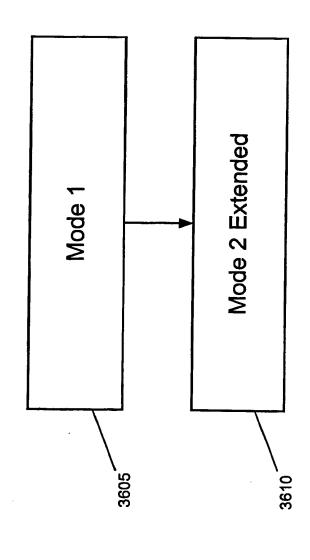
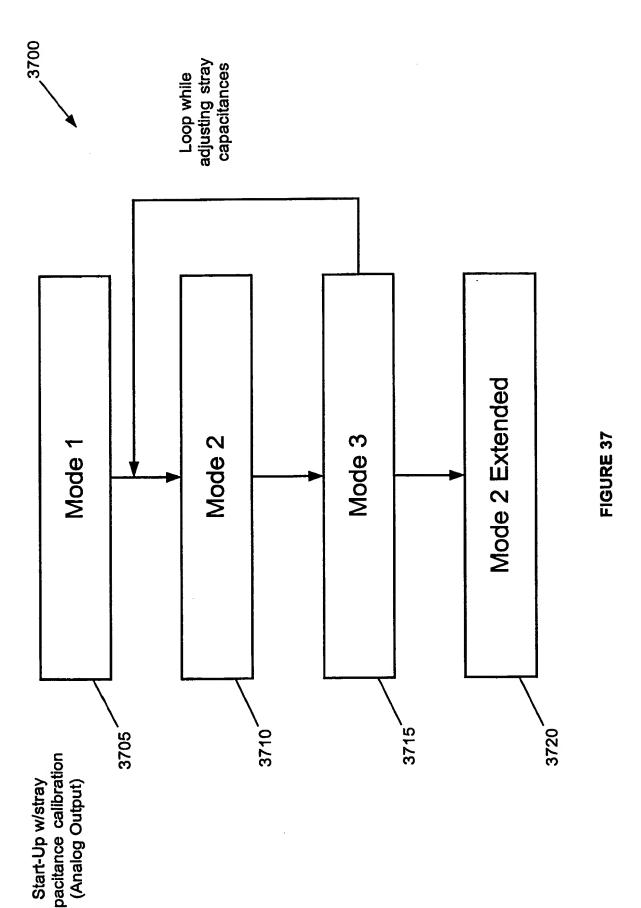


FIGURE 36





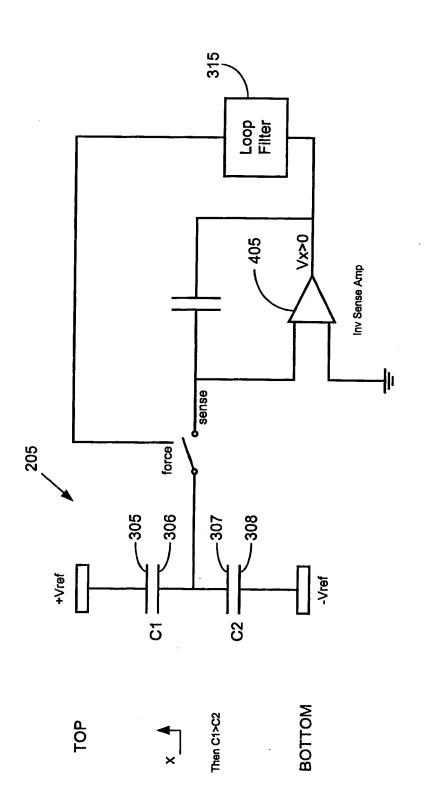
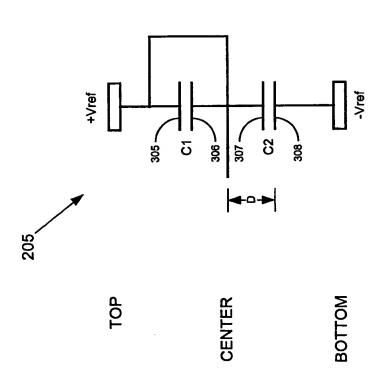
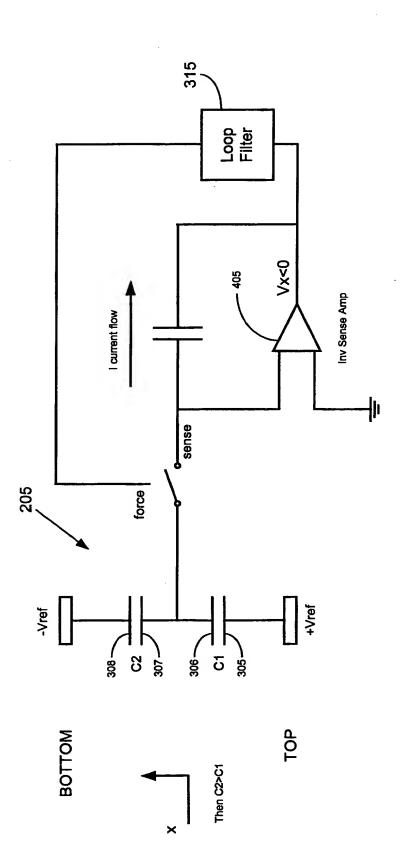


FIGURE 39

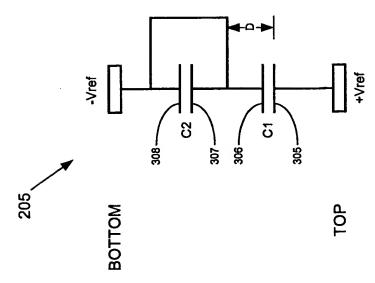








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Force opposing the positive x direction movement caused by the downward acceleration applied to the upside down sensor

F2

FIGURE 41

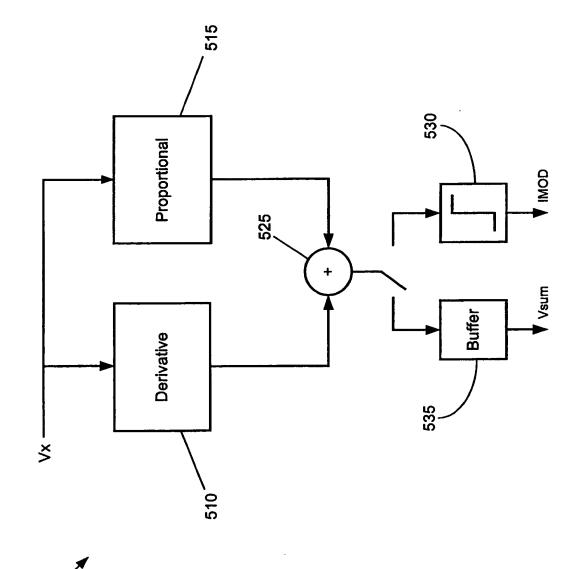
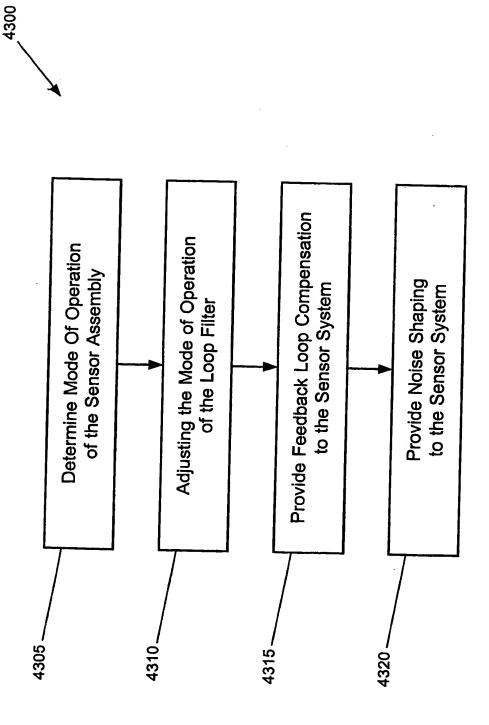


FIGURE 42



**FIGURE 43** 

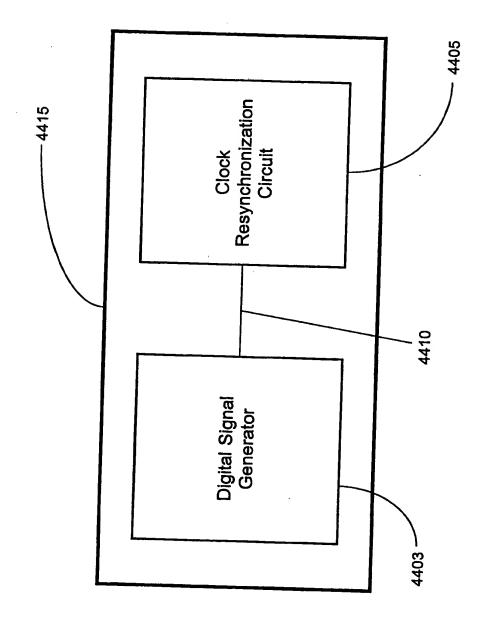
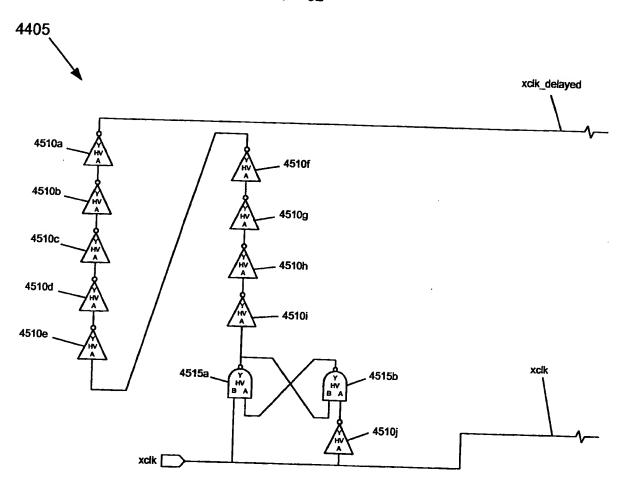


FIGURE 44

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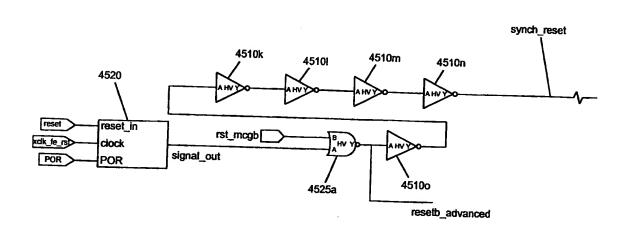


FIGURE 45a

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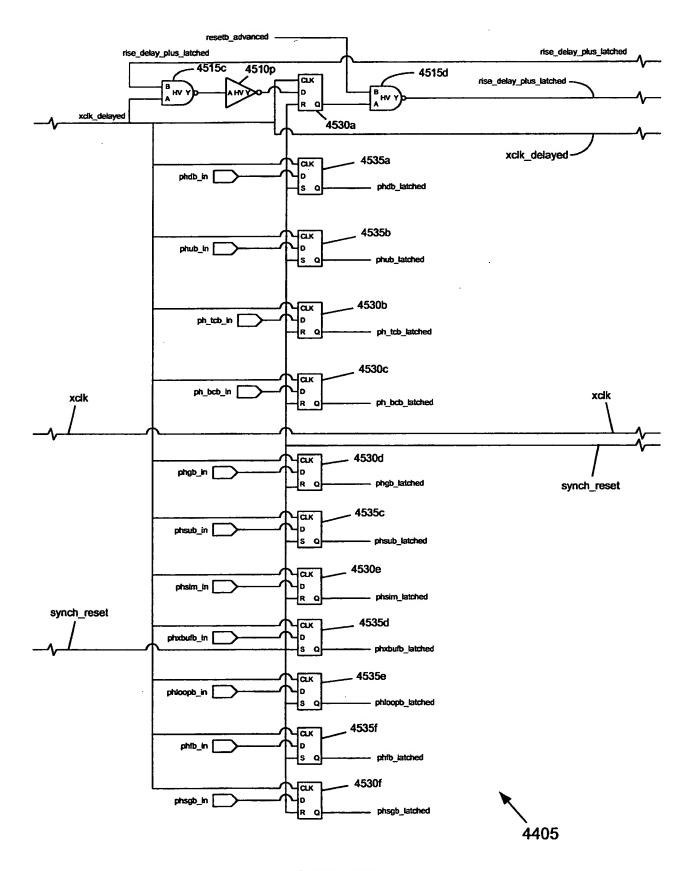
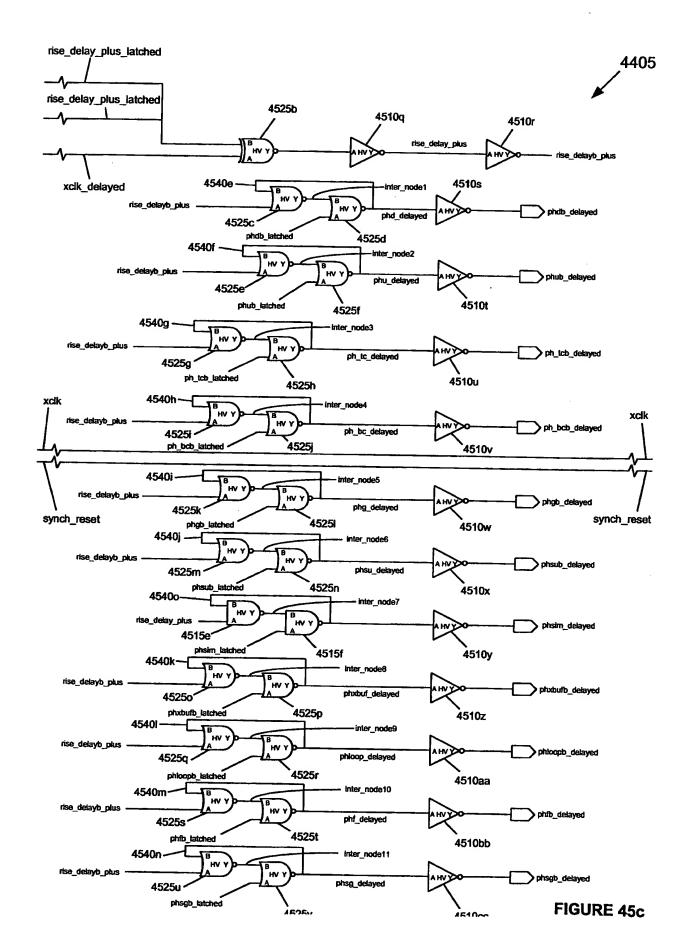


FIGURE 45b

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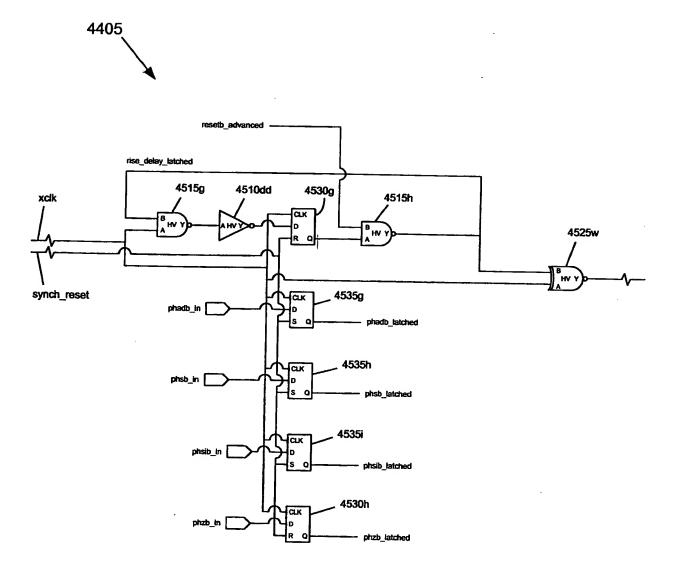


FIGURE 45d



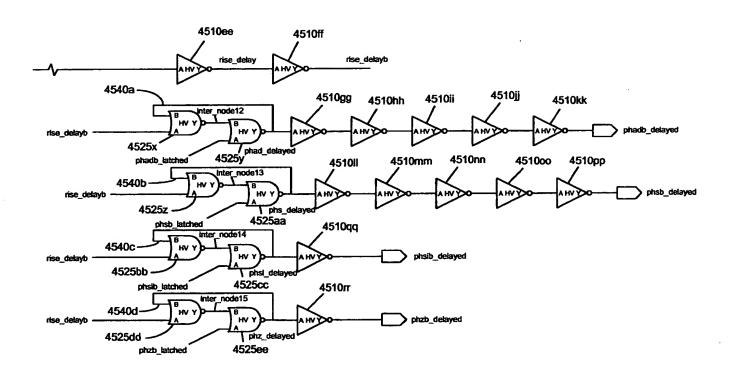
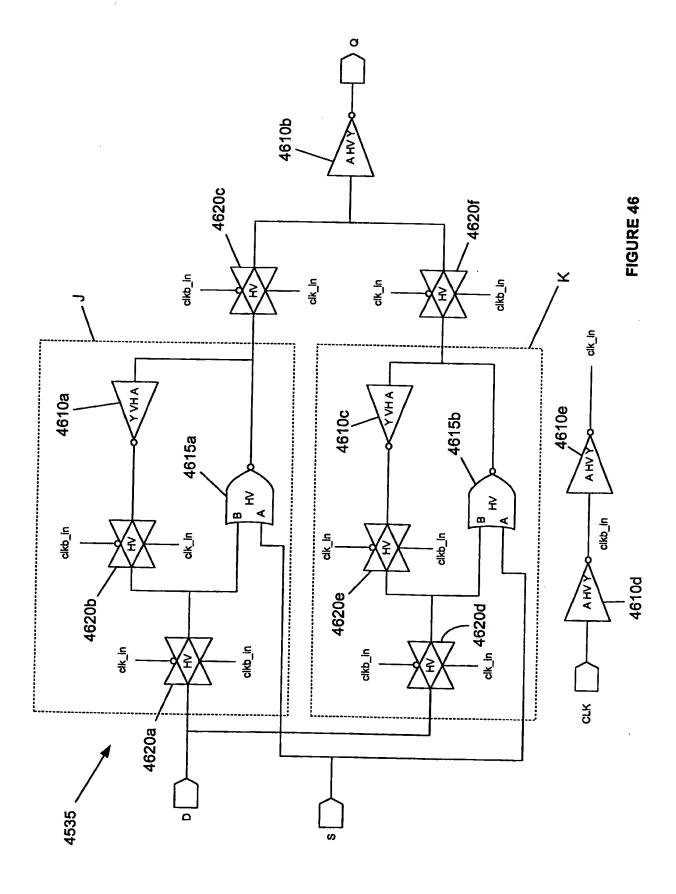
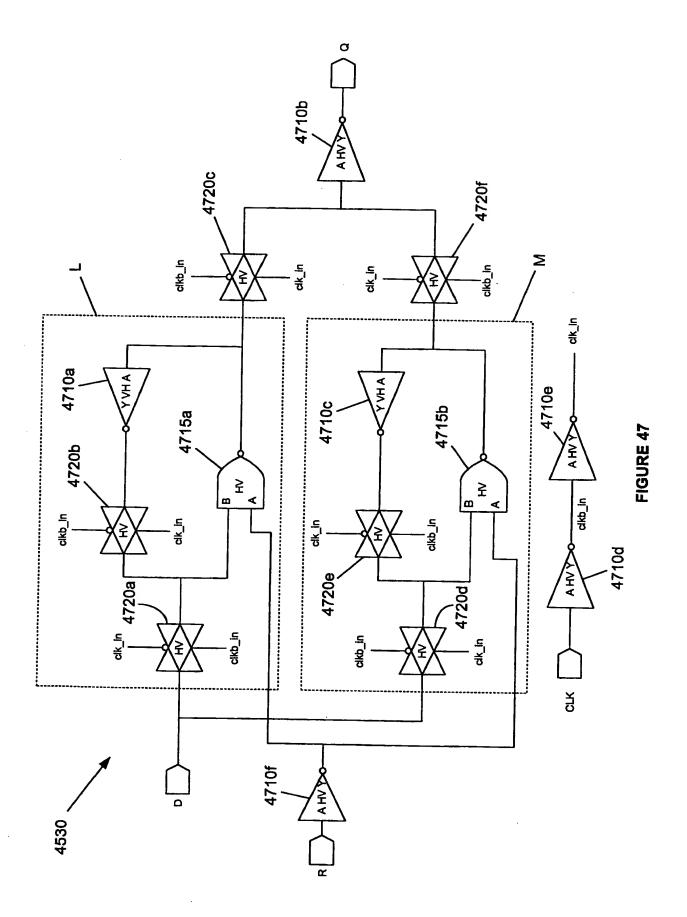
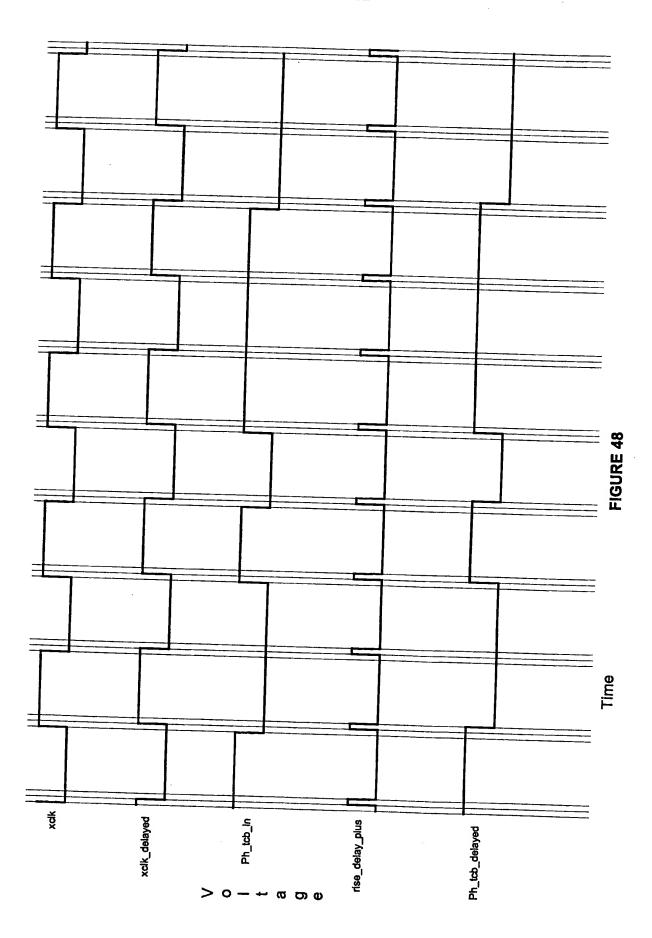


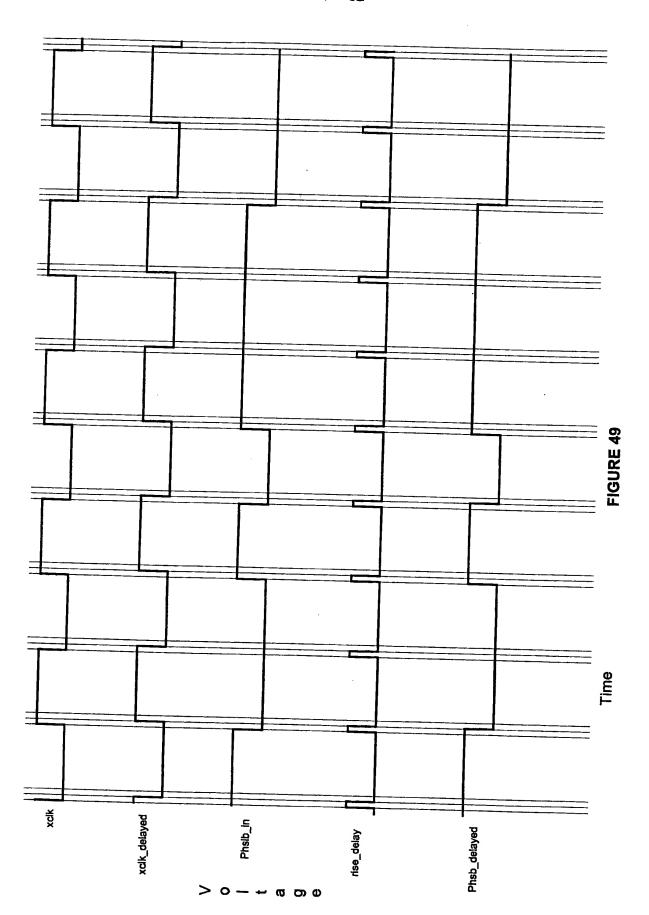
FIGURE 45e







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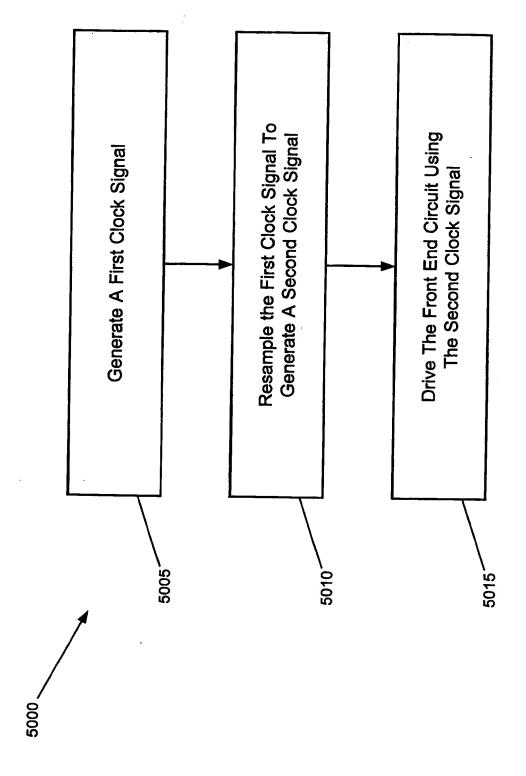


FIGURE 50

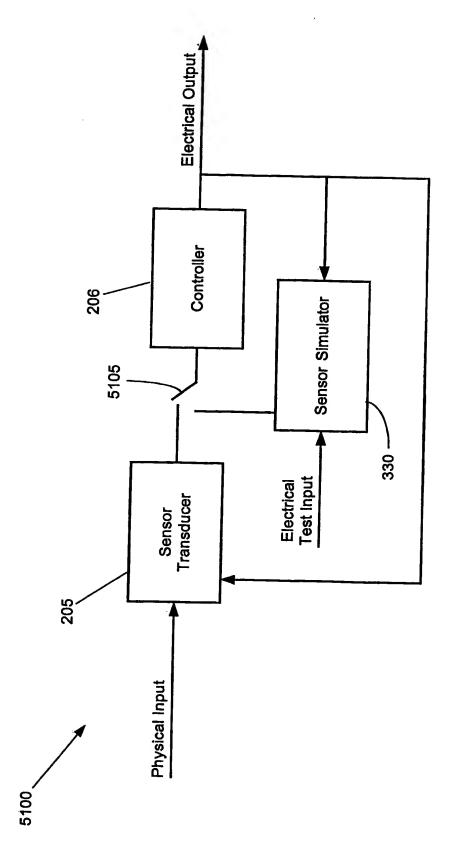
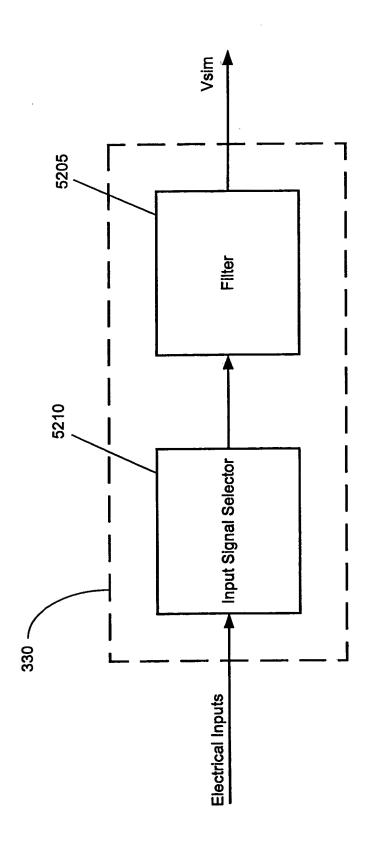


FIGURE 51





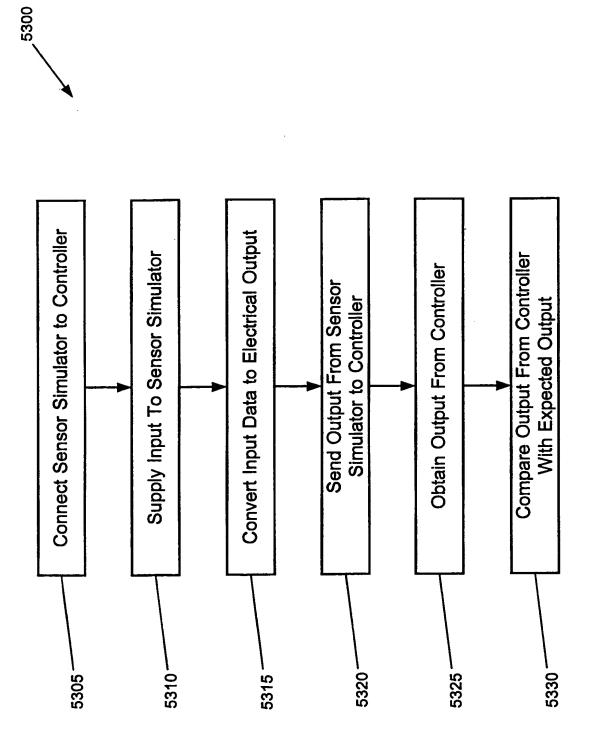
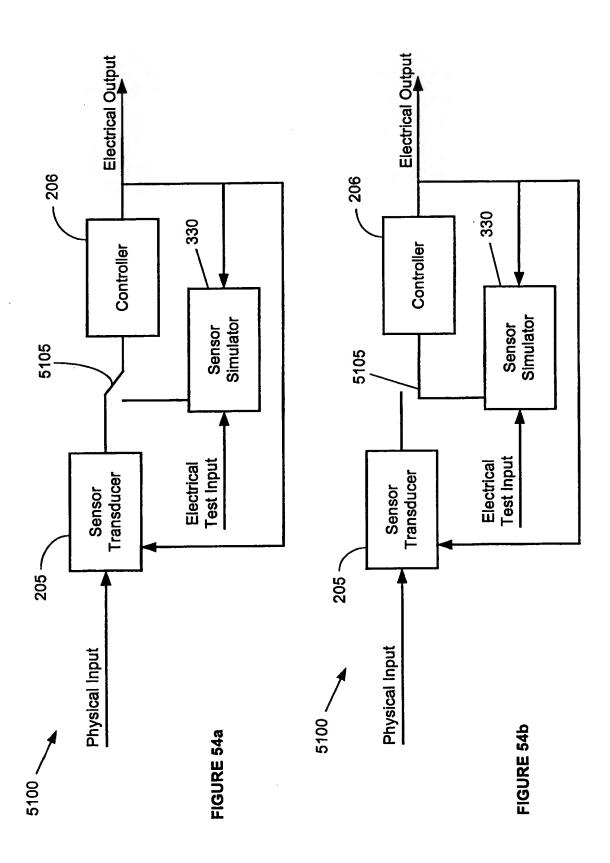


FIGURE 53



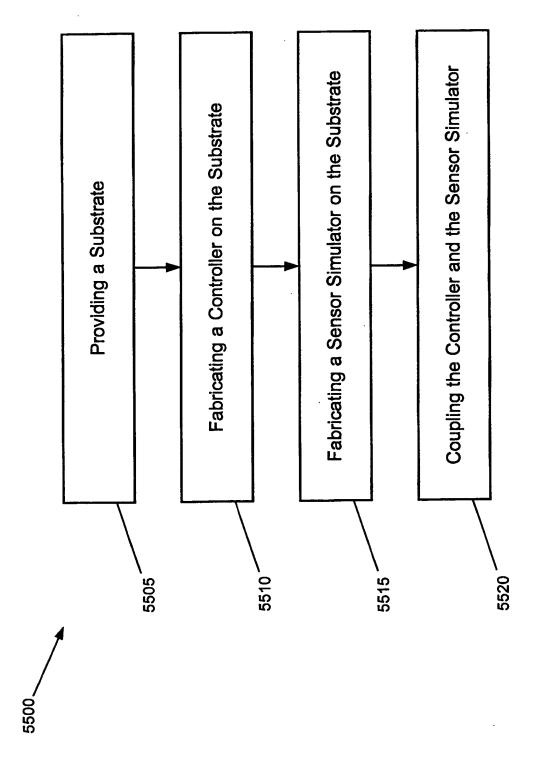


FIGURE 55

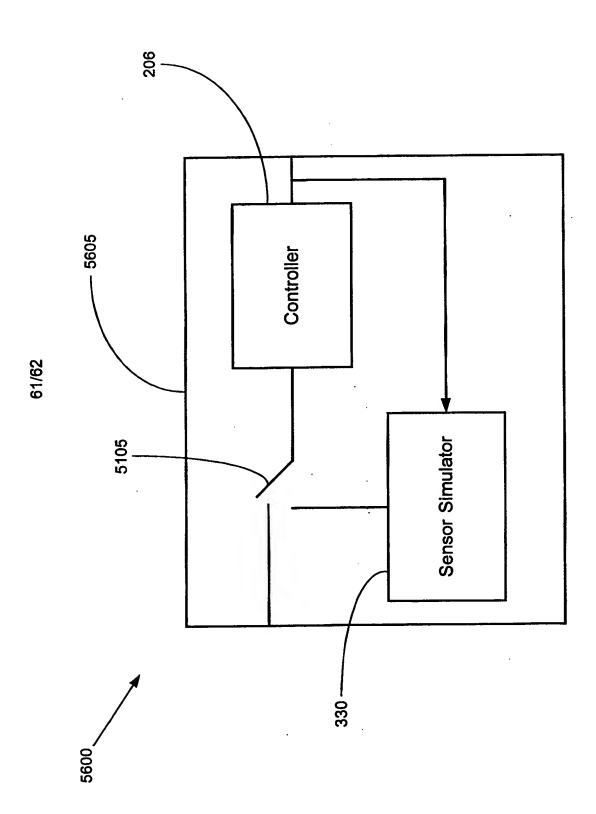
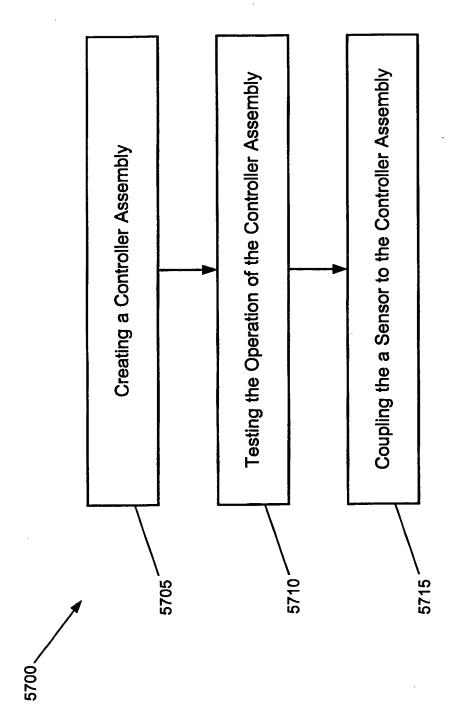


FIGURE 56

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